SIMULATION OF THE COUPLED STRUCTURAL-TRANSPORT RESPONSE OF SOFT TISSUE STRUCTURES USING FINITE ELEMENT MODELS

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INTRODUCTION
Soft tissue structures and associated tissue engineered (TE) materials can be studied using models based on porous media/mixture theories in which multiple charged mobile species are dissolved in a mobile fluid (f) that saturates the “pores” in a highly deformable “solid” fibrous matrix (s) in which fixed charge is present—represented by fixed charge density (FCD). This class of analysis has been utilized for various biological structures including arterial tissue [1], articular cartilage [2], and TE constructs [3]. Finite element models (FEMs) have been developed for the study of these complex problems. Current theoretical models identify various forms for the material properties that can be measured. Here these properties are identified and related mathematically so that they may be utilized in various FEMs. Examples are given to illustrate the effects of finite strain and material properties in FEMs of soft tissue structures.

THEORY
The continuum formulations can be Eulerian or Lagrangian for quasi-static, finite straining of anisotropic materials with no body forces. For clarity, consider three charged mobile species, denoted by α, β = p (+), m (−), b (±) that are dissolved in an incompressible fluid (water) with concentration, cα = dnα / dV or cα = Jncα and valence zα. Assuming the solid is incompressible and saturated by the fluid, the porosity, n = dVf / dV = 1 − J−1(1 − n0) where n0 = dV0f / dV0 = n0(Xs) is the initial (measured) porosity. The FCD, cα = dnα / dV or cα = dncα / dV = Jncα = cα(Xs), i.e. the initial (measured) FCD. Electroneutrality requires that Σzαncα + cF = 0 and an electrical potential, μx will develop or can be applied to the material. The displacements, solid velocity, and relative fluid/species velocites are u = x − Xs, v = u = vi = vi, and vF = n(vF − vi) with γ, δ = f, p, m, b. The deformation gradient, F = ∂x / ∂Xs; volumetric strain, J = dV / dV0; Green’s strain, E = 1/2( F T F − 2I ) ; and Finger’s strain, H = F T F F−1. The total stress (Cauchy), σij = related to the solid stress, σij, and fluid stress, σij = −pδij (hydrostatic fluid pressure, p), as σij = (1 − n)σij − npδij. Relative species flux jα = vi and jα = cαzα. The relative electrical flux (current density), j = i = Σjαzα. The mixed models are based on continuous “primary” fields u, and generalized potentials μx, vz, etc. (see below) that are continuous; whereas the “secondary” fields p, μ, and cα may be discontinuous at material interfaces. The Eulerian phenomenological equations are a basis for all models beginning with the

MIX (Mixture) Model

\[ \bar{\mu}_f = \sum_i f_i \bar{\sigma}_i \] , \( (\bar{\sigma}, \bar{\mu} = s, f, p, m, b) \]

\[ \bar{\mu}_f = [(1 - n)\sigma_{f,i} + n_0 \sigma_{f,i} - (1 - n)\rho_i \bar{\mu}_i], \quad \bar{\mu}_0 = \{n_0 \sigma_{f,i}\}_{ij} \]

\[ -n_0 \sigma_{f,i} - n_0 \rho_i \bar{\mu}_i; \quad \bar{\mu}_0 = -n_0 M_a(F_{\alpha}, \alpha, \mu, \mu^*) \] with material properties: \( f_i \bar{\sigma}_i = f_i \bar{\sigma}_i \); \( f_i \bar{\sigma}_i = 0 \), \( \bar{\sigma}_i = \bar{\sigma}_i + \bar{\mu}(\bar{\alpha}, \bar{\mu}, \mu) \). Introducing definitions of total stress and relative velocities yields the

PM (Porous Media) Model

\[ \sigma_{f,i} = 0, \quad -n_0 f_i \bar{\mu}_i = \sum_\alpha a_{f,i} \bar{\alpha}_i \] ; \( (\gamma, \delta = f, p, m, b) \)

with properties: \( a_{f,i} = f_i + \sum_\alpha f_\alpha a_{\alpha,i} \); \( a_{f,i} = f_i = \bar{f}_i \), etc. Now solve for relative flux in the last two PM equations and introduce the relative flux definitions to obtain

2003 Summer Bioengineering Conference, June 25-29, Sonesta Beach Resort in Key Biscayne, Florida
**MPMT (Mixed Porous Media Transport) Model.**

\[ \sigma_{ij, q} = 0, \quad f_{ij}^{q} = -\nabla \cdot L_{ij}^{\alpha} \mu_{ij} \]

with properties: \( L_{ij}^{\alpha} = n_{i}^{\alpha} a_{i}^{\alpha} \). The total fluid pressure/potential, \( \mu^{\alpha} = p^{\alpha} + \rho^{\alpha} \) and the electro-chemical potentials \( \mu^{\epsilon} = F_{\epsilon} \rho^{\epsilon} + \mu^{\alpha} \) are given in terms of osmotic pressure \( p^{\alpha} = p_{0}^{\alpha} - RT \sum \phi_{i}^{\alpha} c^{i} \) and chemical potential \( \mu^{\alpha} = \mu_{0}^{\alpha} + RT \ln(\gamma_{i} c^{i}) \) to formulate the

**PMT (Porous Media Transport) Model.**

Again \( \sigma_{ij, q} = 0 \) and now the generalized (Eulerian) Darcy law is

\[ v_{i}^{D} = -k_{ij}^{D} \left( p_{j}^{D} + \sum_{\alpha} \left( \sum_{i} b_{ij}^{D} c_{i}^{\alpha} \frac{\partial}{\partial c_{i}^{\alpha}} - \frac{\partial}{\partial c_{i}^{\alpha}} \frac{\partial}{\partial c_{j}^{\alpha}} \right) \right) \]

Fick’s law is \( j_{ij}^{\alpha} = -\sum_{\beta} b_{ij}^{D} c_{j}^{\beta} - \frac{\partial \mu_{ij}^{\alpha}}{\partial c_{j}^{\alpha}} \). The material property functions are the hydraulic permeability, \( k_{ij}^{D} = n_{i}^{D} (a_{i}^{D} - \sum_{\alpha} a_{i}^{\alpha} \sum_{\alpha} a_{\alpha}^{\alpha} \sum_{\alpha} a_{\alpha}^{\alpha})^{-1} \); and the chemical and electrical diffusivities, \( a_{ij}^{\alpha} = \sum_{\beta} b_{ij}^{D} a_{i}^{\beta} = \mu_{ij}^{\alpha} \) (with \( \ell_{ij}^{\alpha} = n_{i} c_{i}^{\alpha} a_{i}^{\alpha} c_{i}^{\beta} \)) and generalized convection coefficients \( b_{ij}^{D} = \sum_{\beta} a_{i}^{\alpha} a_{i}^{\beta} = b_{ij}^{D} \). The PMT properties are related to \( L_{ij}^{D} \) as \( L_{ij}^{D} = k_{ij}^{D} \). Note that ABAQUS FEMs are based on an Eulerian view of the material as a porous hyperelastic material (PHE) that is saturated by an incompressible mobile fluid with no mobile species.

**EMPMT (Electrical Mixed Porous Media Transport) Model.**

Introducing relative current as one flux in \( j_{ij}^{D} = \sum_{\alpha} T_{ij}^{\alpha} J_{ij}^{\alpha} \) and modified potentials defined as \( \phi^{\alpha} = \sum_{\alpha} T_{ij}^{\alpha} \mu^{\alpha} \) (with non-zero terms \( T_{ij}^{\alpha} T_{ij}^{\alpha} = T_{ij}, 1, T_{ij}^{\alpha} = F_{\alpha}, \xi, \eta, f, e, m, b \)) in the MPMT model, \( \sigma_{ij, q} = 0 \) and \( j_{ij}^{D} = -\sum_{\alpha} L_{ij}^{\alpha} \eta_{ij}^{\alpha} \) where \( L_{ij}^{\alpha} = \sum_{\alpha} T_{ij}^{\alpha} T_{ij}^{\alpha} T_{ij}^{\alpha} \).

**Lagrangian EMPMTS MODEL.** The field theory includes the conservation laws \( T_{ij, k} = 0 \ (\dot{T}_{ij} = F_{jk} S_{jk}, \dot{S}_{jj} = JF_{ij}^{\alpha} \sigma_{mm} F_{ij}^{\alpha}) \) and \( \dot{Q} - \dot{J}_{ij}^{\alpha} = 0, \dot{Q} = J, \dot{Q} = 0, \dot{Q} = \dot{\xi}, \dot{Q} = \dot{\eta}; \) constitutive equations, e.g. “effective” stress \( S_{ij} = \dot{S}_{ij}^{\alpha} - Jp^{f} H_{ij} \) and \( \dot{J}_{ij}^{\alpha} = -\sum_{\alpha} \dot{L}_{ij}^{\alpha} \eta_{ij}^{\alpha} \), \( \dot{E}_{ij}^{\alpha} = JF_{ij}^{\alpha} \dot{E}_{ij}^{\alpha} \). Electroneutrality is \( \sum_{\alpha} \dot{z}^{\alpha} \dot{c}^{\alpha} + \dot{c}_{0} = 0 \). Material properties are \( S_{ij}^{\alpha} \) and \( \dot{L}_{ij}^{\alpha} \) that can represent various materials, e.g. for TE materials, \( S_{ij}^{\alpha} \) may take the form for a stiff crushable foam (e.g. ePTFE scaffolds). Compliant materials (e.g. arteries) may be hyperelastic with \( S_{ij}^{\alpha} = \partial U^{\alpha} / \partial E_{ij} \), e.g. “Fung’s” exponential form, \( U^{\alpha} = U^{\alpha}(\varphi) = C_{\alpha}(e^{\varphi} - 1), \dot{E}_{ij}^{\alpha} = \dot{E}_{ij}^{\alpha}(\varphi), \) and \( \varphi = \varphi(E_{ij}, \eta, \dot{\varphi}, T) \).

**FINITE ELEMENT MODELS**

Lagrangian EMPMT FEMs are based on elemental interpolations \( u_{i} = N_{i}^{\alpha} \bar{u}_{i}, \ u_{ij} = N_{ij}^{\alpha} \bar{u}_{ij}, \ \varphi_{i}^{\alpha} = N_{i}^{\alpha} \bar{\varphi}_{i}^{\alpha}, \ \varphi_{ij}^{\alpha} = N_{ij}^{\alpha} \bar{\varphi}_{ij}^{\alpha} \).

Galerkin residuals are \( \Psi_{ij}^{\alpha} = \int N_{i}^{\alpha} \partial j_{ij}^{\alpha} \partial V_{ij}^{\alpha} - \int N_{ij}^{\alpha} \partial j_{ij}^{\alpha} \partial V_{ij}^{\alpha} = 0 \) and \( \Psi_{ij}^{\alpha} = -\int N_{ij}^{\alpha} \dot{Q}^{\alpha} \partial V_{ij}^{\alpha} - \int N_{ij}^{\alpha} \dot{Q}^{\alpha} \partial V_{ij}^{\alpha} = 0 \) that are assembled, boundary/initial conditions imposed, a time integrator applied, and a transient solution for the primary fields is obtained using iterative predictor-corrector algorithms. Iteration is also used to determine the secondary fields (\( p^{\alpha}, \mu^{\alpha}, c^{\alpha} \)) at the Gauss points in each finite element.

**REPRESENTATIVE RESULTS**

An ABAQUS FEM of a large arterial wall was used to predict the relative fluid flux at various pressures in the cardiac cycle. Figure 1 shows fluid flux (at \( P = 120 \text{ mm Hg} \)) that is significantly different from fluid flux associated with constant pressure, indicating a complex convection transport field in the wall during cyclic pressurization.

![Figure 1. ABAQUS FEM of Arterial Wall Fluid Flux](image)

**Figure 2. EMPMT FEM of Concentration and Porosity**

These and other examples demonstrate the capability of these FEMs based on mixed PMT models to simulate coupled structural-transport in complicated biological structures where finite strain occurs. These procedures are currently being used to study vascular wall mechanics and the design of TEVGs including structural response and species transport.

**ACKNOWLEDGEMENT.** NSF GRANT BES-9810098.

**REFERENCES**